Efficient spatio-temporal modelling in practice

Janine Illian

University of Glasgow, Scotland

October 22, 2025

joint work with **many** people, in particular, and most recently with F. Lindgren, **A. Seaton**, **M. Laxton/Morton**, H. Rue, **S. Villejo**, J. Belmont, G. Panunzi, S. Martino...

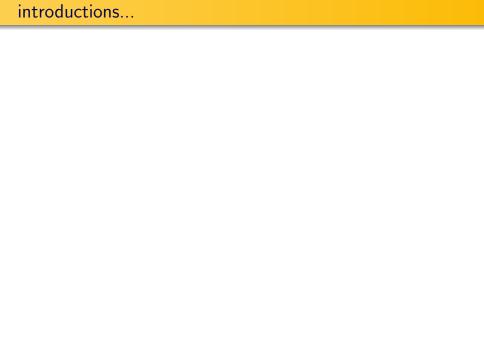
Efficient **and effective** spatio-temporal modelling in practice

Janine Illian

University of Glasgow, Scotland

October 22, 2025

joint work with **many** people, in particular, and most recently with F. Lindgren, **A. Seaton**, **M. Laxton/Morton**, H. Rue, **S. Villejo**, J. Belmont, G. Panunzi, S. Martino...



introductions...

my background: statistical methodology development

introductions...

my background: statistical methodology development spatial and spatio-temporal modelling: focus on spatial point processes

introductions...

my background: statistical methodology development spatial and spatio-temporal modelling: focus on spatial point processes

vision

development of methodology that is

- practically relevant
- realistically complex and
- accessible

approach:

develop **flexible**, computationally **efficient** models that are motivated by strongly **inter-disciplinary** communication, knowledge exchange and research

models of spatial patterns:

⇒ modelling locations and properties ("marks") of objects, events, individuals in space and time

models of spatial patterns:

⇒ modelling **locations and properties ("marks")** of objects, events, individuals in space and time

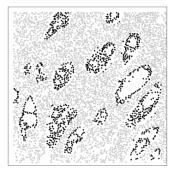
aim

models of spatial patterns:

⇒ modelling **locations and properties ("marks")** of objects, events, individuals in space and time

aim

- examples:
 - cancer cells
 - plants or animals
 - earthquakes
 - terrorist attacks

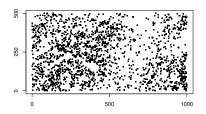


models of spatial patterns:

⇒ modelling **locations and properties ("marks")** of objects, events, individuals in space and time

aim

- examples:
 - cancer cells
 - plants or animals
 - earthquakes
 - terrorist attacks

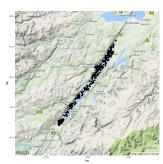


models of spatial patterns:

⇒ modelling **locations and properties ("marks")** of objects, events, individuals in space and time

aim

- examples:
 - cancer cells
 - plants or animals
 - earthquakes
 - terrorist attacks

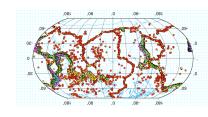


models of spatial patterns:

⇒ modelling locations and properties ("marks") of objects, events, individuals in space and time

aim

- examples:
 - cancer cells
 - plants or animals
 - earthquakes
 - terrorist attacks



models of spatial patterns:

⇒ modelling **locations and properties ("marks")** of objects, events, individuals in space and time

aim

- examples:
 - cancer cells
 - plants or animals
 - earthquakes
 - terrorist attacks

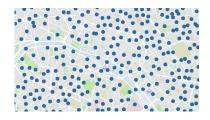


models of spatial patterns:

⇒ modelling **locations and properties ("marks")** of objects, events, individuals in space and time

aim

- examples:
 - cancer cells
 - plants or animals
 - earthquakes
 - terrorist attacks



Point patterns can be modelled by a **point process** N

ullet assigns a count of points to every subset in W; a **measure**; point process N is a **random (counting) measure**

Point patterns can be modelled by a **point process** N

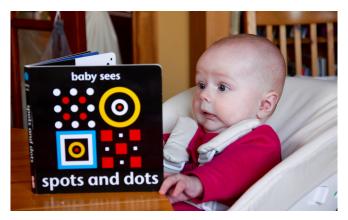
- ullet assigns a count of points to every subset in W; a **measure**; point process N is a **random (counting) measure**
- $\Rightarrow \ \mathsf{mathematically} \ \mathsf{complicated} \ \mathsf{statistical} \ \mathsf{models}$

Point patterns can be modelled by a **point process** N

- ullet assigns a count of points to every subset in W; a **measure**; point process N is a **random (counting) measure**
- ⇒ mathematically complicated statistical models
- \Rightarrow spatial models computationally expensive

Point patterns can be modelled by a **point process** N

- ullet assigns a count of points to every subset in W; a **measure**; point process N is a **random (counting) measure**
- ⇒ mathematically complicated statistical models
- ⇒ spatial models computationally expensive



vision

development of methodology that

- is practically relevant and realistically complex,
- accounts for reality of data collection and
- is accessible to users

vision

development of methodology that

- is practically relevant and realistically complex,
- accounts for reality of data collection and
- is accessible to users

→ making the very theoretic point processes relevant in practice

steps...

• development of models that are relevant in practice

- development of models that are relevant in practice
 - → complex spatio-temporal point process models

- ◆ development of models that are relevant in practice
 → complex spatio-temporal point process models
- development of efficient software to fit these models

- development of software that is user friendly and accounts for observation processes

- development of software that is user friendly and accounts for observation processes
 - \sim inlabru

- development of software that is user friendly and accounts for observation processes
 - \sim inlabru
- work hard on the communicating these methods and their results to users...



inlabru		

inlabru

 \Rightarrow wrapper around R-INLA* + extra functionality:

inlabru

- ⇒ wrapper around R-INLA* + extra functionality:
 - R-library that makes fitting of "tricky" models (e.g. multi-likelihood models, spatial point processes) less fiddly than R-INLA

inlabru

- ⇒ wrapper around R-INLA* + extra functionality:
 - R-library that makes fitting of "tricky" models (e.g. multi-likelihood models, spatial point processes) less fiddly than R-INLA
 - takes observation process into account (e.g. issues of detectability)

inlabru

- \Rightarrow wrapper around R-INLA* + extra functionality:
 - R-library that makes fitting of "tricky" models (e.g. multi-likelihood models, spatial point processes) less fiddly than R-INLA
 - takes observation process into account (e.g. issues of detectability)
 - allows for non-linear predictors defined by general R expressions

inlabru

- \Rightarrow wrapper around R-INLA* + extra functionality:
 - R-library that makes fitting of "tricky" models (e.g. multi-likelihood models, spatial point processes) less fiddly than R-INLA
 - takes observation process into account (e.g. issues of detectability)
 - allows for non-linear predictors defined by general R expressions

in essence: integrated fitting of observation process and (ecological) process of interest

inlabru

- \Rightarrow wrapper around R-INLA* + extra functionality:
 - R-library that makes fitting of "tricky" models (e.g. multi-likelihood models, spatial point processes) less fiddly than R-INLA
 - takes observation process into account (e.g. issues of detectability)
 - allows for non-linear predictors defined by general R expressions

in essence: integrated fitting of observation process and (ecological) process of interest observation process is an operation on the point pattern - e.g. a thinning

* R-INLA is the R-library implementation of integrated nested Laplace approximation (INLA)

benefits of INLA...

basing our approach on INLA allows us to:

 use computationally efficient model fitting approaches for many realistically complex models in space and time;

basing our approach on INLA allows us to:

 use computationally efficient model fitting approaches for many realistically complex models in space and time; not just point processes!

basing our approach on INLA allows us to:

- use computationally efficient model fitting approaches for many realistically complex models in space and time; not just point processes!
- develop flexible (continuous) approximations (the "SPDE approach")
- → model in large, complex domains (e.g. on the sphere)

basing our approach on INLA allows us to:

- use computationally efficient model fitting approaches for many realistically complex models in space and time; not just point processes!
- develop flexible (continuous) approximations (the "SPDE approach")
- → model in large, complex domains (e.g. on the sphere)
 - account for barriers in space

basing our approach on INLA allows us to:

- use computationally efficient model fitting approaches for many realistically complex models in space and time; not just point processes!
- develop flexible (continuous) approximations (the "SPDE approach")
- → model in large, complex domains (e.g. on the sphere)
 - account for barriers in space
 - use all the functionality available in R-INLA general context

studies use a **feasible** sampling approach for specific system or species

studies use a **feasible** sampling approach for specific system or species

applied statistics – method development:

studies use a **feasible** sampling approach for specific system or species

applied statistics - method development:

- develop separate methodology for
- each observation process along with
- a separate software package along with
- a new training course...

not very efficient with ever increasing amounts of data and new observations processes

studies use a **feasible** sampling approach for specific system or species

applied statistics - method development:

- develop separate methodology for
- each observation process along with
- a separate software package along with
- a new training course...

not very efficient with ever increasing amounts of data and new observations processes

→ inlabru provides a general framework

most applications in (statistical) ecology...

 epidemiology happens in space and time – accounting for spatial dependence in statistical models is important

- epidemiology happens in space and time accounting for spatial dependence in statistical models is important
- spatial distribution of, e.g., infected/non-infected individuals can be seen as **marked point pattern**

- epidemiology happens in space and time accounting for spatial dependence in statistical models is important
- spatial distribution of, e.g., infected/non-infected individuals can be seen as **marked point pattern**
- joint modelling of marks and pattern, but also of different data sources

- epidemiology happens in space and time accounting for spatial dependence in statistical models is important
- spatial distribution of, e.g., infected/non-infected individuals can be seen as **marked point pattern**
- joint modelling of marks and pattern, but also of different data sources
- making the modelling relevant to users: impacting on policy result visualisation

- epidemiology happens in space and time accounting for spatial dependence in statistical models is important
- spatial distribution of, e.g., infected/non-infected individuals can be seen as **marked point pattern**
- joint modelling of marks and pattern, but also of different data sources
- making the modelling relevant to users: impacting on policy result visualisation

joint modelling: climate data – Philippines

combining data from different sources

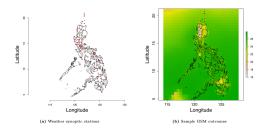
 \bullet 57 weather stations across the >7000 islands forming the Phillippines

joint modelling: climate data – Philippines

- 57 weather stations across the > 7000 islands forming the Phillippines
- Global Spectral Model (GSM), a numerical weather prediction model maintained by the Japan Meteorological Agency

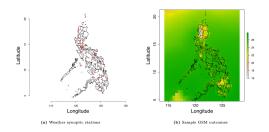
joint modelling: climate data - Philippines

- ullet 57 weather stations across the > 7000 islands forming the Phillippines
- Global Spectral Model (GSM), a numerical weather prediction model maintained by the Japan Meteorological Agency



joint modelling: climate data - Philippines

- ullet 57 weather stations across the > 7000 islands forming the Phillippines
- Global Spectral Model (GSM), a numerical weather prediction model maintained by the Japan Meteorological Agency



- weather stations: sparse but good quality
- weather model: good coverage, but not correct
- → model accounts for difference in data quality

joint modelling: climate data - England and Wales

combining data from different sources

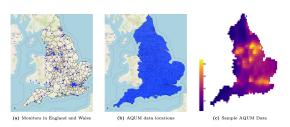
 Automatic Urban and Rural Network (AURN) in England and Wales; pollutants such as NO2, O3, PM10 and PM2.5l locations (a)

joint modelling: climate data - England and Wales

- Automatic Urban and Rural Network (AURN) in England and Wales; pollutants such as NO2, O3, PM10 and PM2.5I locations (a)
- Air Quality Unified Model (AQUM); weather and chemical transport model: hourly estimates of pollutant concentrations in a 12 km2 grid locations (b) and sample outcome NO2 (c)

joint modelling: climate data – England and Wales

- Automatic Urban and Rural Network (AURN) in England and Wales; pollutants such as NO2, O3, PM10 and PM2.5I locations (a)
- Air Quality Unified Model (AQUM); weather and chemical transport model: hourly estimates of pollutant concentrations in a 12 km2 grid locations (b) and sample outcome NO2 (c)



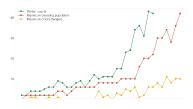
reintroduction of cranes into the UK – background



- UK resident population extirpated in the 16th century
- re-established by a single breeding pair in 1979 through immigration from mainland Europe
- population boosted by further immigrants and a reintroduction project from 2010-2014
- only breed in wetlands...

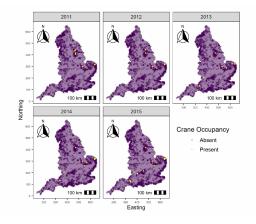


modelling in fragmented habitat



- range expansion which wetland habitats are likely to be colonised?
- looking at presence of the species in relation to environmental covariates alone could be misleading
- → some habitats may be outside of the population's current range

- spatial point pattern: reflects wetland locations
- marks: occupancy (nesting/no nesting) over time (2010 -2015)
- → point pattern reflects observation process



joint model with two responses and likelihoods:

wetlands: log Gaussian Cox process

- wetlands: log Gaussian Cox process
- spatio-temporal probability of crane presence, conditional on the locations of wetlands

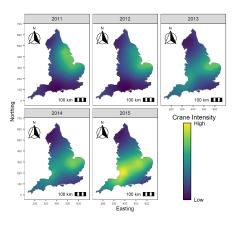
- wetlands: log Gaussian Cox process
- spatio-temporal probability of crane presence, conditional on the locations of wetlands
- shared Gaussian random field reflecting wetland intensity

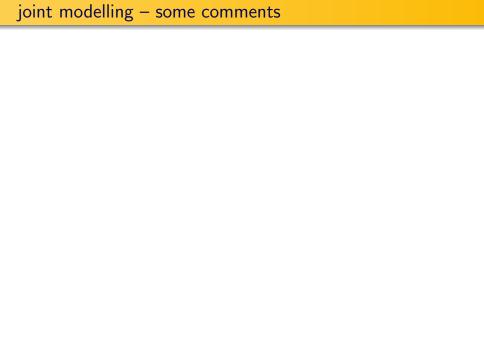
- wetlands: log Gaussian Cox process
- spatio-temporal probability of crane presence, conditional on the locations of wetlands
- shared Gaussian random field reflecting wetland intensity
- additional random field reflecting crane presence through space and time

- wetlands: log Gaussian Cox process
- spatio-temporal probability of crane presence, conditional on the locations of wetlands
- shared Gaussian random field reflecting wetland intensity
- additional random field reflecting crane presence through space and time
- → distinguishing between unfavourable habitat and favourable habitat not within reach yet

reintroduction of cranes into the UK – some results

predictions in space and time...





where is Scotland?

where is Scotland?



where is Scotland?



it's more complicated...

where is Scotland?



it's more complicated...

current model cannot account for spread further North

where is Scotland?



it's more complicated...

- current model cannot account for spread further North
- perfect detection of cranes inlabru can account for detection issues

joint modelling - some comments

where is Scotland?



it's more complicated...

- current model cannot account for spread further North
- perfect detection of cranes inlabru can account for detection issues
- different quality of data accounted for in models

- model fitting fast complex models can be fitted
- very general methodology and software

- model fitting fast complex models can be fitted
- very general methodology and software
- as new observation processes become available

- model fitting fast complex models can be fitted
- very general methodology and software
- as new observation processes become available
- ightharpoonup existing functionality of R-INLA and inlabru available

- model fitting fast complex models can be fitted
- very general methodology and software
- as new observation processes become available
- ightharpoonup existing functionality of R-INLA and inlabru available

benefits - implemented in inlabru:

- model fitting fast complex models can be fitted
- very general methodology and software
- as new observation processes become available
- $\,\,\rightarrow\,\,$ existing functionality of R-INLA and inlabru available

example:

can combine different data types very conveniently into a joint model with several likelihoods

benefits - implemented in inlabru:

- model fitting fast complex models can be fitted
- very general methodology and software
- as new observation processes become available
- ightarrow existing functionality of R-INLA and inlabru available

example:

can combine different data types very conveniently into a joint model with several likelihoods

here: survey data and data from numerical models – relevance to epidemiology...

benefits - implemented in inlabru:

- model fitting fast complex models can be fitted
- very general methodology and software
- as new observation processes become available
- ightharpoonup existing functionality of R-INLA and inlabru available

example:

can combine different data types very conveniently into a joint model with several likelihoods

here: survey data and data from numerical models – relevance to epidemiology...

point pattern used as observation process

benefits - implemented in inlabru:

- model fitting fast complex models can be fitted
- very general methodology and software
- as new observation processes become available
- ightharpoonup existing functionality of R-INLA and inlabru available

example:

can combine different data types very conveniently into a joint model with several likelihoods

here: survey data and data from numerical models – relevance to epidemiology...

point pattern used as observation process but also:

movement data combined with survey data

benefits - implemented in inlabru:

- model fitting fast complex models can be fitted
- very general methodology and software
- as new observation processes become available
- ightarrow existing functionality of R-INLA and inlabru available

example:

can combine different data types very conveniently into a joint model with several likelihoods

here: survey data and data from numerical models – relevance to epidemiology...

point pattern used as observation process but also:

movement data combined with survey data citizen science data combined with survey data



 models are complex spatio-temporal models



- models are complex spatio-temporal models
- containing difficult statistical "elements"



- models are complex spatio-temporal models
- containing difficult statistical "elements"
- these "building blocks" account for e.g. spatial autocorrelation



- models are complex spatio-temporal models
- containing difficult statistical "elements"
- these "building blocks" account for e.g. spatial autocorrelation
- but: also represent structures that reflect reflect processes, e.g. behaviour, dispersal limitation



building blocks have a role

• a statistical role



- a statistical role
- an applied (e.g. ecological role): represent structures of interest



- a statistical role
- an applied (e.g. ecological role): represent structures of interest
- \rightarrow these need to be communicated



- a statistical role
- an applied (e.g. ecological role): represent structures of interest
- \rightarrow these need to be communicated
- $\, \leadsto \,$ these form part of the output



- a statistical role
- an applied (e.g. ecological role): represent structures of interest
- → these need to be communicated
- \rightarrow these form part of the output
- → these need to be interpreted and plotted



building blocks have a role

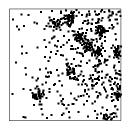
- a statistical role
- an applied (e.g. ecological role): represent structures of interest
- → these need to be communicated
- $\,\leadsto\,$ these form part of the output
- these need to be interpreted and plotted



What properties of these building blocks do we want to interpret and represent – and how?

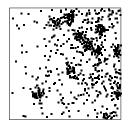
example: spatial point process models

• log Gaussian Cox process; random intensity $\Lambda(s) = \exp(X(s)),$



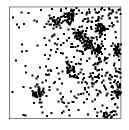
example: spatial point process models

• log Gaussian Cox process; random intensity $\Lambda(s) = \exp(X(s)),$ where X is a Gaussian random field



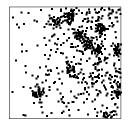
example: spatial point process models

- log Gaussian Cox process; random intensity $\Lambda(s) = \exp(X(s)),$ where X is a Gaussian random field
- ullet X is approximated by an **SPDE**



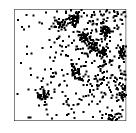
example: spatial point process models

- log Gaussian Cox process; random intensity $\Lambda(s) = \exp(X(s)),$ where X is a Gaussian random field
- ullet X is approximated by an **SPDE**



example: spatial point process models

- log Gaussian Cox process; random intensity $\Lambda(s) = \exp(X(s)),$ where X is a Gaussian random field
- X is approximated by an **SPDE**



building blocks difficult explain...

example: communicating the modelling approach

 concept of a spatial point process model as such difficult



example: communicating the modelling approach

- concept of a spatial point process model as such difficult
- random intensity, Gaussian random field and SPDE as well



example: communicating the modelling approach

- concept of a spatial point process model as such difficult
- random intensity, Gaussian random field and SPDE as well
- observation process thinning of spatial point process; easier to communicate



example: communicating the modelling approach

- concept of a spatial point process model as such difficult
- random intensity, Gaussian random field and SPDE as well
- observation process thinning of spatial point process; easier to communicate



the approximated intensity and its properties play important ecological role

study aim and data collection:

 bird conservation – estimating animal abundance of endangered and endemic bird species



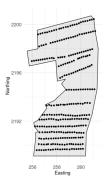
study aim and data collection:

- bird conservation estimating animal abundance of endangered and endemic bird species
- data collected at observation points along transects; point transects along line transects



study aim and data collection:

- bird conservation estimating animal abundance of endangered and endemic bird species
- data collected at observation points along transects; point transects along line transects
- integrated model: thinned point process model, modelling both species distribution and observation process



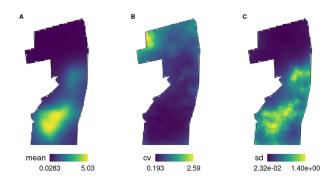
study aim and data collection:

- bird conservation estimating animal abundance of endangered and endemic bird species
- data collected at observation points along transects; point transects along line transects
- integrated model: thinned point process model, modelling both species distribution and observation process
- Bayesian approach, fitted in inlabru



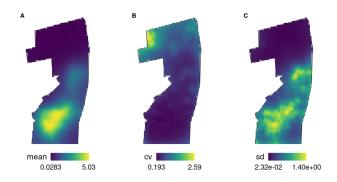
visualizing the results, standard approach

• predicted mean of the posterior intensity field, A



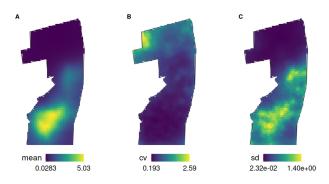
visualizing the results, standard approach

- predicted mean of the posterior intensity field, A
- map of the **coefficient of variation** (CV), B



visualizing the results, standard approach

- predicted mean of the posterior intensity field, A
- map of the coefficient of variation (CV), B
- standard deviation of the posterior intensity field, C



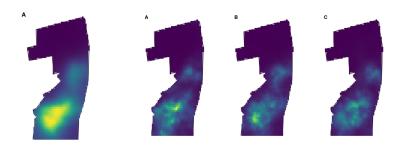
limitations of mapped summaries

• **posterior predicted mean**: will always be smoother than realisations

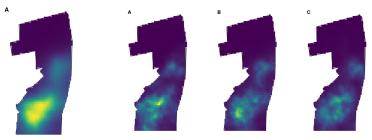
- posterior predicted mean: will always be smoother than realisations
- realisations have a finer-grained spatial structure than can be seen in the mean



- posterior predicted mean: will always be smoother than realisations
- realisations have a finer-grained spatial structure than can be seen in the mean
- misleading sense of homogeneity



- posterior predicted mean: will always be smoother than realisations
- realisations have a finer-grained spatial structure than can be seen in the mean
- misleading sense of homogeneity
- **visualisation:** multiple realisations, e.g. as an animation; also communicating uncertainty



limitations of mapped summaries

• CV map: intended to communicate uncertainty



- CV map: intended to communicate uncertainty
- however: CV values will be higher in regions of low predicted intensity



- CV map: intended to communicate uncertainty
- however: CV values will be higher in regions of low predicted intensity
- highlights regions of relatively lower intensity but not necessarily higher overall uncertainty



- CV map: intended to communicate uncertainty
- however: CV values will be higher in regions of low predicted intensity
- highlights regions of relatively lower intensity but not necessarily higher overall uncertainty
- also: variable sampling effort across study region; not clear what impact this has on the CV map



- CV map: intended to communicate uncertainty
- however: CV values will be higher in regions of low predicted intensity
- highlights regions of relatively lower intensity but not necessarily higher overall uncertainty
- also: variable sampling effort across study region; not clear what impact this has on the CV map
- hard to interpret!



limitations of mapped summaries

• SD map: also intended to communicate uncertainty



- SD map: also intended to communicate uncertainty
- however: variance higher where intensity is higher; maps similar to mean map



- SD map: also intended to communicate uncertainty
- however: variance higher where intensity is higher; maps similar to mean map
- default colour scale tends to show spatial variation in uncertainty – difference might be irrelevant in context

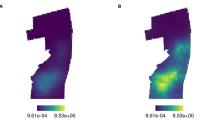


- SD map: also intended to communicate uncertainty
- however: variance higher where intensity is higher; maps similar to mean map
- default colour scale tends to show spatial variation in uncertainty – difference might be irrelevant in context
- hard to interpret!

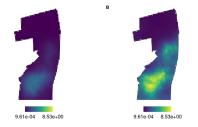


limitations of mapped summaries

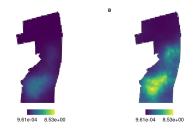
• quantile maps: lower and upper quantiles (95% credible interval for each prediction location)



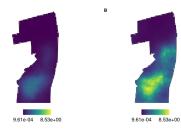
- quantile maps: lower and upper quantiles (95% credible interval for each prediction location)
- independent summaries of the posterior intensity field at each location



- quantile maps: lower and upper quantiles (95% credible interval for each prediction location)
- independent summaries of the posterior intensity field at each location
- map shows thousands of such quantiles side by side in a single image



- quantile maps: lower and upper quantiles (95% credible interval for each prediction location)
- independent summaries of the posterior intensity field at each location
- map shows thousands of such quantiles side by side in a single image
- no single realisation looks like this



- quantile maps: lower and upper quantiles (95% credible interval for each prediction location)
- independent summaries of the posterior intensity field at each location
- map shows thousands of such quantiles side by side in a single image
- no single realisation looks like this
- likely to be misinterpreted!





some suggestions:

 consider a priori, relevant values of animal density and acceptable levels of uncertainty in context and aims

some suggestions:

- consider a priori, relevant values of animal density and acceptable levels of uncertainty in context and aims
- consider jointly the predicted values of the posterior intensity field (i.e. non independently)

some suggestions:

- consider a priori, relevant values of animal density and acceptable levels of uncertainty in context and aims
- consider *jointly* the predicted values of the posterior intensity field (i.e. non independently)
- → avoids presenting independent quantiles side by side

some suggestions:

- consider a priori, relevant values of animal density and acceptable levels of uncertainty in context and aims
- consider *jointly* the predicted values of the posterior intensity field (i.e. non independently)
- ightarrow avoids presenting independent quantiles side by side
- constructs summary maps that consider the joint probability across prediction locations

excursion sets (Bolin and Lindgren 2015)

• joint probability of events across a set of locations

- joint probability of events across a set of locations
- avoid the interpretability issues of the quantile or exceedance threshold maps

- joint probability of events across a set of locations
- avoid the interpretability issues of the quantile or exceedance threshold maps
- require the user to specify thresholds of interest for the random field and acceptable levels of uncertainty

- joint probability of events across a set of locations
- avoid the interpretability issues of the quantile or exceedance threshold maps
- require the user to specify thresholds of interest for the random field and acceptable levels of uncertainty
- avoid the issue of a default colour scale

- joint probability of events across a set of locations
- avoid the interpretability issues of the quantile or exceedance threshold maps
- require the user to specify thresholds of interest for the random field and acceptable levels of uncertainty
- avoid the issue of a default colour scale
- ullet positive excursion set: area having an abundance of >1 bird per hectare with probability 0.95



- joint probability of events across a set of locations
- avoid the interpretability issues of the quantile or exceedance threshold maps
- require the user to specify thresholds of interest for the random field and acceptable levels of uncertainty
- avoid the issue of a default colour scale
- ullet positive excursion set: area having an abundance of > 1 bird per hectare with probability 0.95
- "core region" for the 'akepa population conservation importance



effective modelling - conclusions

 visually communicating output from spatio-temporal models is hard

effective modelling - conclusions

- visually communicating output from spatio-temporal models is hard
- the role of a "building block" in a model needs to be interpreted in context

effective modelling – conclusions

- visually communicating output from spatio-temporal models is hard
- the role of a "building block" in a model needs to be interpreted in context
- → visualisation needs to reflect the role and context

effective modelling – conclusions

- visually communicating output from spatio-temporal models is hard
- the role of a "building block" in a model needs to be interpreted in context
- → visualisation needs to reflect the role and context
- effective visualisation requires effective communication and engagement with the (ecological) context

 efficient model fitting in (relatively) general software environment provides flexibility

- efficient model fitting in (relatively) general software environment provides flexibility
- effective and efficient modelling is an ongoing dialogue between model developers/modellers and "end-users"

- efficient model fitting in (relatively) general software environment provides flexibility
- effective and efficient modelling is an ongoing dialogue between model developers/modellers and "end-users"
- model development and presentation of outcomes not in isolation

- efficient model fitting in (relatively) general software environment provides flexibility
- effective and efficient modelling is an ongoing dialogue between model developers/modellers and "end-users"
- model development and presentation of outcomes not in isolation
- not all end-users are the same e.g. quantitative ecologists vs. policy makers