# **Influence of human behaviors on the spread of an epidemic**

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# **MOVI 2024 – Colloque sur l'épidémiologie comportementale** Rennes, 31 mai 2024



# <span id="page-1-0"></span>**[Outline](#page-1-0)**

 $\triangleright$  Spatial heterogeneity and human mobilities:  $\rightsquigarrow$  complex networks of epidemic models joint work with Cristiana J. Silva

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 $\blacktriangleright$  Influence of human behaviors:  $\rightsquigarrow$  coupling with a discrete-probabilistic process joint work with Cristiana J. Silva and Arnaud Banos

 $\triangleright$  On-going work:

 $\rightsquigarrow$  continuous domains  $\rightsquigarrow$  abstraction and verification of hybrid dynamical systems

# <span id="page-6-0"></span>**Context: "[an epidemic of](#page-6-0) [epidemics](#page-6-0)"**

"A major change happened in the 1960s: the emergence of a globalized epidemiological environment specific to the Anthropocene, the new geological era that began with the industrial revolution.

Today, new plagues are appearing. Are we witnessing the last outbreak of plagues with the emergence of the Ebola or Zika?"



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#### $\blacktriangleright$  Global warming

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#### $\blacktriangleright$  Deforestation

[Wilcox & B. Ellis (2006). Forests and emerging infectious diseases of humans. UNASYLVA-FAO.]

#### $\blacktriangleright$  Air traffic



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[Wilcox & B. Ellis (2006). Forests and emerging infectious diseases of humans. UNASYLVA-FAO.]

#### $\blacktriangleright$  Human behaviors

[Epstein et al. (2008). Coupled contagion dynamics of fear and disease : mathematical and computational explorations. PLoS One.]

# **A huge literature...**

#### $\rightarrow$  Numerous books, thousands of papers...



 $4/40$ 

 $\begin{array}{l} \displaystyle \alpha_{\mathcal{R},\mathcal{R},\mathcal{L}_{\mathcal{M}_{\mathcal{R}}}} \sum_{\mathcal{R} \in \mathcal{R}_{\mathcal{M}_{\mathcal{R}}}} \sum_{\mathcal{R} \in \mathcal{R}_{\mathcal{M}_{\mathcal{R}}}} \sum_{\mathcal{R} \in \mathcal{R}_{\mathcal{R}} \cup \{\mathcal{R} \in \mathcal{R}_{\mathcal{R}}\}} \epsilon_{\mathcal{R}} \otimes \mathcal{R}_{\mathcal{R}_{\mathcal{R}}}} \\ \displaystyle \alpha_{\mathcal{R}} \in \mathcal{R}_{\mathcal{R}} \times \mathcal{R}_{\math$ 

# **A huge literature...**



# **Differential equations**

▶ The SIR model (S: susceptible, I: infected, R: recovered):

$$
\begin{cases}\n\frac{dS}{dt} = -\frac{\beta IS}{N},\\
\frac{dI}{dt} = +\frac{\beta IS}{N} - \gamma I,\\
\frac{dR}{dt} = +\gamma I.\n\end{cases}
$$

Important hypotheses:

 $\rightsquigarrow$  the transmission of the disease is much faster than the dynamics of birth and death,

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Important hypotheses:

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 $\rightsquigarrow$  large population.

 $\triangleright$  Multiple variants: additional compartments, reaction-diffusion, fractional diffusion, time delays, age structure...

#### Agent-based models, cellular automata, transition systems...



Source: https://cloud.anylogic.com/models





#### $\blacktriangleright$  Existence of irregular oscillations



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- $\blacktriangleright$  The environment is not necessarily periodic
- $\rightarrow$  First step: provide an heterogeneous spatial structure
	- $\rightarrow$  geographical network
- $\rightsquigarrow$  Second step: integrate the impacts of human behaviors
	- $\rightarrow$  hybrid dynamical system

<span id="page-24-0"></span>**[Spatial heterogeneity and human](#page-24-0) [mobilities: complex networks of](#page-24-0) [epidemic models](#page-24-0)**

We consider a population affected by a HIV/AIDS epidemic. The SICA model [Silva & Torres (2017)] is given by

$$
\begin{cases}\n\dot{S} = \Lambda - \beta (I + \eta_C C + \eta_A A) S - \mu S, \\
\dot{I} = \beta (I + \eta_C C + \eta_A A) S - (\rho + \phi + \mu) I + \omega C + \alpha A, \\
\dot{C} = \phi I - (\omega + \mu) C, \\
\dot{A} = \rho I - (\alpha + \mu + d) A.\n\end{cases}
$$

*S*: number of susceptible individuals;

- *I*: HIV-infected individuals with no clinical symptoms of AIDS;
- *C*: HIV-infected individuals under ART treatment;
- *A*: HIV-infected individuals with AIDS clinical symptoms;
- *N*: total population.

# **Parameters of the SICA model**

- Λ Recruitment rate
- *µ* Natural death rate
- *β* HIV transmission rate
- *η<sup>C</sup>* Modification parameter
- *η<sup>A</sup>* Modification parameter
- *φ* HIV treatment rate for *I* individuals
- *ρ* Default treatment rate for *I* individuals
- *α* AIDS treatment rate
- *ω* Default treatment rate for *C* individuals
- *d* AIDS induced death rate

 $\triangleright$  The SICA model admits a disease-free equilibrium (DFE) given by  $\Sigma_0 = \left(\frac{\Lambda}{\mu}\right)$  $\frac{\Lambda}{\mu}, 0, 0, 0\Big)$  .

Its basic reproduction number  $R_0$  (expected average number of new infections produced by a single infected individual) is given by

$$
R_0 = \frac{S^0 \beta \left[ \xi_2 \left( \xi_1 + \rho \eta_A \right) + \eta_C \phi \xi_1 \right]}{\mu \left[ \xi_2 \left( \rho + \xi_1 \right) + \phi \xi_1 + \rho d \right] + \rho \omega d}.
$$

 $\blacktriangleright$  The disease free equilibrium  $\Sigma_0$  is globally asymptotically stable if  $R_0 < 1$ .

 $\blacktriangleright$  The SICA model admits an endemic equilibrium  $\Sigma_{+}$ , which is globally asymptotically stable if  $R_0 > 1$ .

 $\blacktriangleright$  The SICA model can be rewritten:

$$
\dot{x} = f(x, p), \quad x = (S, I, C, A)^T, \quad p = (\Lambda, \beta, \dots, \alpha, d).
$$

## **Case study: Cape Verde archipelago**



# **Case study: Cape Verde archipelago**



#### $\blacktriangleright$  Ideas:

 $\rightarrow$  we can model the archipelago by a graph,

 $\rightsquigarrow$  we can couple each vertex of the graph with an instance of the SICA model.

 $\blacktriangleright$  We consider a graph  $\mathscr G$  with  $n$  vertices.

 $\blacktriangleright$  We divide the vertices into two subsets  $\mathscr{V}_1$ ,  $\mathscr{V}_2$ .

 $\blacktriangleright$  We couple:

 $\rightsquigarrow$  the vertices of  $\mathcal{V}_1$  with an instance of the SICA model for which  $R_0 < 1$ ,

 $\rightsquigarrow$  the vertices of  $\mathscr{V}_2$  with an instance of the SICA model for which  $R_0 > 1$ .

 $\blacktriangleright$  The complex network is determined by:

$$
\dot{X} = F(X, P) + LHX,
$$

where

$$
X = (x_1, \ldots, x_n)^T \in (\mathbb{R}^4)^n,
$$
  
\n
$$
HX = (Hx_1, \ldots, Hx_n)^T \in (\mathbb{R}^4)^n,
$$
  
\n
$$
P = (p_1, \ldots, p_n) \in (\mathbb{R}^{10})^n,
$$

and *F* determines the internal dynamic of each vertex:

$$
F(X, P) = (f(x_1, p_1), \ldots, f(x_n, p_n))^{T}.
$$

 $\blacktriangleright$  Explicit equations of the complex network:

$$
\begin{cases}\n\dot{S}_j = \Lambda_j - \beta_j (I_j + \eta_{C,j} C_j + \eta_{A,j} A_j) S_j - \mu_j S_j + \varepsilon_S \sum_{k=1}^n L_{j,k} S_k, \\
\dot{I}_j = \beta_j (I_j + \eta_{C,j} C_j + \eta_{A,j} A_j) S_j - (\rho_j + \phi_j + \mu_j) I_j \\
+ \omega_j C_j + \alpha_j A_j + \varepsilon_I \sum_{k=1}^n L_{j,k} I_k, \\
\dot{C}_j = \phi_j I_j - (\omega_j + \mu_j) C_j + \varepsilon_C \sum_{k=1}^n L_{j,k} C_k, \\
\dot{A}_j = \rho_j I_j - (\alpha_j + \mu_j + d_j) A_j + \varepsilon_A \sum_{k=1}^n L_{j,k} A_k.\n\end{cases}
$$

### **Connections**

 $\blacktriangleright$  *L* is the matrix of connectivity: for each edge  $(k, j) \in \mathscr{E}$ ,  $k \neq j$ , we have  $L_{j,k} > 0$ . If  $(k, j) \notin \mathscr{E}$ ,  $k \neq j$ , we set  $L_{j,k} = 0$ . The diagonal coefficients satisfy

$$
L_{j,j} = -\sum_{\substack{k=1\\k\neq j}}^n L_{k,j}.
$$

 $\blacktriangleright$  Finally, *H* is the matrix of the coupling strengths and it is given by

$$
H = \begin{bmatrix} \varepsilon_S & 0 & 0 & 0 \\ 0 & \varepsilon_I & 0 & 0 \\ 0 & 0 & \varepsilon_C & 0 \\ 0 & 0 & 0 & \varepsilon_A \end{bmatrix},
$$

with non negative coefficients  $\varepsilon_S$ ,  $\varepsilon_I$ ,  $\varepsilon_C$  and  $\varepsilon_A$ .

# ▶ Theorem (Cantin & Silva 2019)

The complex network of SICA models admits a unique disease-free equilibrium  $\Sigma_0$ , which is globally asymptotically stable in the region  $\Omega$  defined by

$$
\Omega = \left\{ (x_j)_{1 \leq j \leq 4n} \in (\mathbb{R}^+)^{4n} ; \sum_{j=1}^{4n} x_j \leq \frac{\sum \Lambda_j}{\min \mu_j} \right\}.
$$

provided

$$
\frac{\Lambda_0}{\mu_0}\frac{\mathcal{N}_i}{\mathcal{D}_i} < 1,
$$

for all  $i \in \{1, \ldots, n\}$ , with known constants  $\mathcal{N}_i$ ,  $\mathcal{D}_i$ .

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for all  $i \in \{1, \ldots, n\}$ , with known constants  $\mathcal{N}_i$ ,  $\mathcal{D}_i$ .

 $\rightsquigarrow$  Local basic reproduction number:  $R_{0,i} = \frac{\Lambda_i}{\Lambda_i}$  $\mu_i$ N*i*  $\frac{\partial}{\partial \overline{\partial}}$ .


Two-nodes network. Green node:  $R_{0,1}$  < 1. Red node:  $R_{0,2}$  > 1.



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Influence of the coupling strengths  $\varepsilon_S$ ,  $\varepsilon_I$ ,  $\varepsilon_C$  and  $\varepsilon_A$  on the basic reproduction numbers  $R_{0,1}$  and  $R_{0,2}$ .

 $\triangleright$  We introduce the final level of infected individuals:

$$
L_f = \sum_{j=1}^{n} [I_j(T) + C_j(T) + A_j(T)].
$$

 $\triangleright$  Question: can we find a network topology that minimizes  $L_f$ ?

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 $\blacktriangleright$  Idea: we generate a sample of randomly generated topologies, by choosing a random number of edges  $1 \leq |\mathscr{E}| \leq 72$ , and a random subset of  $|\mathscr{E}|$  edges.



# **Optimal topologies**



Numerical results for two samples of 1400 randomly generated topologies. Green dotted vertical line: level of infected individuals without coupling. Optimal topology: green circle.

 $\triangleright$  A near-optimal topology detected by the random simulation:

$$
\mathscr{E} = \{ [1, 3], [2, 9], [5, 6], [3, 7], [7, 9], [2, 7], [1, 9], [6, 2], [6, 4], [2, 8], [5, 2], [8, 1], [1, 5], [1, 4] \}.
$$

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$$



# <span id="page-43-0"></span>**[Influence of human behaviors:](#page-43-0) [hybrid dynamical systems](#page-43-0)**

 $\triangleright$  Assume a population of individuals is subject to a complex evolution process which cannot be described at a single scale.  $\triangleright$  We construct a hybrid model by coupling a system of ordinary differential equations and a discrete process, which can be derived from an agent-based model.

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 $\blacktriangleright$  The population is divided into several disjoint groups

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X=(x_1,\ldots,x_n).
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 $\triangleright$  We consider a discrete sequence of times  $(t_s)$ .  $\blacktriangleright$  We introduce, for  $s \geq 0$ , the abstract hybrid problem

$$
\begin{cases}\n(\Im \mathfrak{C}) & X(t_0) = X_0, \quad \lambda_0 \in J, \\
(\mathfrak{M}_s) & \dot{X}(t) = F(X(t), \lambda_s), \quad t_s < t \le t_{s+1}, \\
(\mathfrak{m}_s) & \lambda_{s+1} = G(X(t_{s+1}), \lambda_s).\n\end{cases}
$$

## **Construction of a class of abstract hybrid models**

 $\blacktriangleright$  *F* is a function defined in  $E \times J$  with values in  $\mathbb{R}^n$ , where *E* is an open subset of  $\mathbb{R}^n$  and  $J$  is an open subset of  $\mathbb{R}^d$ .

- $\blacktriangleright$  *G* is a function defined in  $E \times J$  with values in *J*.
- $\triangleright$  (IC) determines the initial condition  $(X_0, \lambda_0) \in E \times J$ .

 $\blacktriangleright$  ( $\mathfrak{M}_s$ ) is an ordinary differential equation which determines the macroscopic part of the hybrid problem.

 $\bullet$  ( $m_s$ ) is a discrete mapping which determines the microscopic part of the hybrid problem.

## **Timeline of the hybrid model**



Timeline of the hybrid model. At  $t = t_0$ , the initial condition ( $\mathfrak{IC}$ ) gives  $(X_0, \lambda_0) \in E \times J$ . On each interval  $[t_s, t_{s+1}]$ , the macroscopic part (M*s*) is determined by an ordinary differential equation. At each time step  $t = t_s$ , the microscopic part  $(\mathfrak{m}_s)$ follows from a discrete mapping which is derived from an agent-based model.

 $\blacktriangleright$  **Assumption 1.** The function  $F$  involved in the macroscopic part  $(\mathfrak{M}_s)$  of the hybrid problem is  $\mathscr{C}^1(E\times J).$ 

I **Assumption 2.** There exists a compact set *K* ⊂ *E* such that, for all  $(X_0, \lambda_0) \in K \times J$ , each local solution  $X(t, X_0)$  of the Cauchy problem

$$
X(t_0) = X_0, \quad \dot{X}(t) = F(X(t), \lambda_0)
$$

defined on  $[t_0, t_0 + T]$  with  $T > 0$  satisfies

 $X(t, X_0) \in K$ 

for all  $t \in [t_0, t_0 + T]$ .

 $\triangleright$  **Assumption 3.** The function *G* involved in the microscopic part  $(m<sub>s</sub>)$  of the hybrid problem is continuous in  $E \times J$ .

#### ▶ Theorem (Cantin Silva Banos, 2022)

Let the assumptions 1, 2 hold. Then for all  $(X_0, \lambda_0) \in K \times J$ , the hybrid problem admits a unique global solution  $X(t, X_0, \lambda_0)$ defined on  $[t_0, +\infty)$ .

If moreover assumption 3 holds, then each global solution  $X(t, X_0, \lambda_0)$  of the hybrid problem is continuous at  $(X_0, \lambda_0)$ , uniformly on each finite time interval  $[t_0, t_0 + T]$  with  $T > 0$ , that is, for each  $T > 0$  and each  $\varepsilon > 0$ , there exists  $\delta > 0$  such that

$$
||X(t, X_0+h, \lambda_0+k)-X(t, X_0, \lambda_0)||_{\mathbb{R}^n}<\varepsilon,
$$

for all  $t \in [t_0, t_0 + T]$ , provided that  $||(h, k)||_{\mathbb{R}^n \times \mathbb{R}^d} < \delta$ .

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 $\blacktriangleright$  What if *G* is discontinuous?  $\rightsquigarrow$  High sensitivity of the model.

### **Irregular oscillations**

 $\blacktriangleright$  We suppose that there exist two distinct parameters sets  $\Lambda_1 \subset J$ and  $\Lambda_2 \subset J$  with  $\Lambda_1 \cap \Lambda_2 = \emptyset$ .

Assume  $\Sigma_1$  is an equilibrium point of the equation

 $\dot{X} = F(X, \lambda_1)$ ,

for each  $\lambda_1 \in \Lambda_1$ , and  $\Sigma_2$  is an equilibrium point of the equation

 $\dot{X} = F(X, \lambda_2),$ 

for each  $\lambda_2 \in \Lambda_2$ .

 $\triangleright$  We introduce the minimum step of the timeline  $\{t_s\}$ :

$$
\tau = \min_{s \ge 0} |t_s - t_{s+1}|.
$$

#### **Fi** Theorem

Suppose that assumptions 1, 2 hold. Assume that  $\Sigma_1$  is globally asymptotically stable in  $W_1 \subset K$  for each  $\lambda_1 \in \Lambda_1$ ,  $\Sigma_2$  is globally asymptotically stable in  $W_2 \subset K$  for each  $\lambda_2 \in \Lambda_2$ . Assume moreover that  $\Sigma_1 \in W_2$ ,  $\Sigma_2 \in W_1$  and  $G(Y, \lambda) \in \Lambda_2$  if Y is near  $\Sigma_1$  and  $\lambda \in \Lambda_1$ ,  $G(Y, \lambda) \in \Lambda_1$  if Y is near  $\Sigma_2$  and  $\lambda \in \Lambda_2$ .

Then every solution  $X(t, X_0, \lambda_0)$  of the hybrid problem starting from  $(X_0, \lambda_0) \in W_1 \times \Lambda_1$  admits irregular oscillations, that is, oscillations between a neighborhood  $\mathcal{N}_1$  of  $\Sigma_1$  and a neighborhood  $\mathcal{N}_2$  of  $\Sigma_2$ , provided the minimum step  $\tau$  of the timeline is sufficiently large.

 $\blacktriangleright$  We consider the  $SAIRP$  model with refractory behaviors Silva et al. 2021]:

$$
\begin{cases}\n\dot{S} = \Lambda - \beta(1 - p(1 - u))\frac{(\theta A + I)}{N}S - \phi p(1 - u)S + \omega P - \mu S, \\
\dot{A} = \beta(1 - p(1 - u))\frac{(\theta A + I)}{N}S - \nu A - \mu A, \\
\dot{I} = \nu A - \delta I - \mu I, \\
\dot{R} = \delta I - \mu R, \\
\dot{P} = \phi p(1 - u)S - \omega P - \mu P.\n\end{cases}
$$

 $\triangleright$  *S*: susceptible individuals, *A*: asymptomatic infected individuals, *I*: active infected individuals, *R*: removed (including recovered and COVID-19 induced deaths); *P*: protected individuals.

- Λ Recruitment rate
- *µ* Natural death rate
- *θ* Infectiousness of the asymptomatic infected individuals
- *v* Transfer rate from *A* to *I*
- *q* Fraction of *A* individuals that are confirmed to be infected
- *φ* Transfer rate from *S* to *P*
- *δ* Transfer rate from *I* to *R*
- *ω* Transfer rate from *P* to *S*
- p Fraction of protected individuals
- *u* Refractory or opposition behaviors to the protection strategy

 $\triangleright$  We assume that the individuals are spatially distributed into a finite number of regions  $D_1, \ldots, D_m$  with  $m \geq 1$ ; some of these regions are interconnected and individuals present a spatial mobility from one region to another.



 $\blacktriangleright$  The dynamics of the epidemic is modeled at the macroscopic scale by a complex network of ordinary differential equations:

$$
\frac{dx_{i,j}}{dt} = f_j(x_i, \alpha_i) + \sigma_j \sum_{k=1}^n L_{i,k} x_{j,k}, 1 \le j \le 5, 1 \le i \le m, t \ge 0.
$$
\n<sup>30/40</sup>

 $\triangleright$  We cannot follow the trajectory of a single individual during the macroscopic process.

 $\triangleright$  We cannot follow the trajectory of a single individual during the macroscopic process.

 $\blacktriangleright$  Assume  $X(t, X_s, \lambda_s)$  solves  $(\mathfrak{M}_s)$  on  $[t_s, t_{s+1}]$ . For each sub-population  $x_{ij}$  of type  $j$  in each region  $D_i$ , we evaluate  $x_{ij}(t_{s+1})$  and we compute  $N_{ij}(t_{s+1}) = [x_{ij}(t_{s+1})]$ . We then  $\mathfrak{a}_i$  introduce the agents:  $\mathfrak{A}_{ij} = \{ \mathfrak{a}_{ij}^1, \mathfrak{a}_{ij}^2, \ldots, \mathfrak{a}_{ij}^{N_{ij}} \}.$ ► We generate a social network over the groups  $(\mathfrak{A}_{ij})_{1\leq j\leq 5}$  of each region *D<sup>i</sup>* by running a graph generation algorithm.



We assume that agents model citizens or decision makers and focus on two types of actions.

▶ Action 1. In each region  $D_i$ ,  $1 \leq i \leq m$ , decision makers evaluate the rate  $\rho_I(D_i,t_{s+1})$  of infected individuals.

- If the rate  $\rho_I(D_i,t_{s+1})$  overcomes a given threshold  $\mathcal{T}_1$ , that is  $\rho_I(D_i,t_{s+1}) > \mathcal{T}_1$ , then decision makers decide to increase the fraction *p<sup>i</sup>* of individuals.
- Else, the fraction of protected individuals is maintained.
- If at least one of the rates  $\rho_I(D_i,t_{s+1})$ ,  $1 \leq i \leq m$ , overcomes a second threshold  $T_2 > T_1$ , then decision makers decide to confine the individuals in their region.
- Else, then decision makers reestablish the mobilities.

Action 2. In each region  $D_i$ , agents  $\mathfrak{a}_{ij}^g$  observe the types of their neighbors. Among these neighbors, each agent a evaluates the number  $\mathfrak{N}(I, \mathfrak{a}, t_{s+1})$  of infected neighbors.

- If the rate of infected neighbors overcomes a given threshold  $\mathcal{T}_3$ , then citizens decide to be in opposition with the protection strategy.
- Else, then citizens accept to decrease their level of opposition.

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- Else, then citizens accept to decrease their level of opposition.

 $\triangleright$  The two-actions protocol defines a discrete mapping

$$
\lambda_{s+1} = G(X(t_{s+1}), \lambda_s),
$$

which determines the microscopic part (m*s*) of a hybrid model.

## ▶ Theorem (Cantin Silva Banos, 2022)

 $(1)$  For any  $X_0 \in (\mathbb{R}^+)^{5m}$  and any  $\lambda_0 \in J$ , the hybrid model admits a unique solution denoted by  $X(t, X_0, \lambda_0)$ , defined on  $[0, \infty)$ , whose components are non-negative.

(2) Furthermore, the hybrid model admits a compact and positively invariant region *K*.

(3) The hybrid model admits solutions exhibiting irregular solutions between two equilibrium points (DFE and EE).

 $\triangleright$  Solutions exhibiting irregular solutions can easily be generated by forcing a variation of the parameter *p*.



 $\rightsquigarrow$  Roughly:  $p = 0.95 \Leftrightarrow$  confinement,  $p = 0.2 \Leftrightarrow$  end of confinement.

Sc. 3: postponed extinction of the disease by opposition behaviors



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<span id="page-68-0"></span>**[On going work](#page-68-0)**

## **Hybrid dynamical system with continuous domains**

 $\triangleright$  We consider a reaction-diffusion epidemic model

$$
\begin{cases} \n\partial_t S = d_1 \Delta S + \mu N - \mu S - \beta S I, & x \in \Omega, \quad t > 0, \\ \n\partial_t I = d_2 \Delta I - (\mu + \nu) I + \beta S I, & x \in \Omega, \quad t > 0, \n\end{cases}
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in a bounded domain  $\Omega$ , coupled with a discrete-probabilistic process along a timeline of step *τ >* 0.

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 $\triangleright$  Questions:

- well-posedness of the hybrid model?
- stability of the equilibrium points?
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▶ Questions:

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$\triangleright$  We consider a continuous dynamical system  $S_{\lambda}(t)$  depending on a parameter  $\lambda$ , with uniform phase space  $\Phi$ , coupled with a discrete probabilistic process Θ along a timeline of step *τ >* 0.

 $\blacktriangleright$  How to verify dynamical properties of the hybrid system  $(S)$ resulting from the coupling?

 $\rightsquigarrow$  We can abstract the dynamics of the hybrid system as a Markov decision process  $(M)$  and verify relevant properties directly on  $(M)$ , with *Model Checking* algorithmic techniques of theoretical computer science.

 $\blacktriangleright$  The abstraction requires to consider a discretization of the hybrid model  $(S)$ .

# **Abstraction and verification of piecewise deterministic Markov processes**



How to abstract a property of  $(S)$  as a property of  $(M)$ ?

 $\blacktriangleright$  Is the abstraction a "surjective" mapping?

 $\blacktriangleright$  Can we "inverse" the verification' of  $(M)$ ?

 $\blacktriangleright$  It is difficult to model human behaviors and their influence on the spread of an epidemic.

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 $\rightsquigarrow$  Joint work with Cristiana J. Silva, Arnaud Banos

[Mathematical analysis of a hybrid model: Impacts of individual behaviors on the spreading of an epidemic, Networks and Heterogeneous Media (2022)]

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# **Thank you for your attention!**